int t=2;

int e=3;

void setup()

{

Serial.begin(9600);

pinMode(t,OUTPUT);

pinMode(e,INPUT);

pinMode(12,OUTPUT);

}

void loop()

{

//ultrasonic sensor

digitalWrite(t,LOW);

digitalWrite(t,HIGH);

delayMicroseconds(10);

digitalWrite(t,LOW);

float dur=pulseIn(e,HIGH);

float dis=(dur\*0.0343)/2;

Serial.print("Distance is: ");

Serial.println(dis);

//LED ON

if(dis>=100)

{

digitalWrite(8,HIGH);

digitalWrite(7,HIGH);

}

//Buzzer For ultrasonic Sensor

if(dis>=100)

{

for(int i=0; i<=30000; i=i+10)

{

tone(12,i);

delay(1000);

noTone(12);

delay(1000);

}

}